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Three Dimensional Motion Trail Model for Gesture Recognition

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OUTLINE

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4. Conclusions

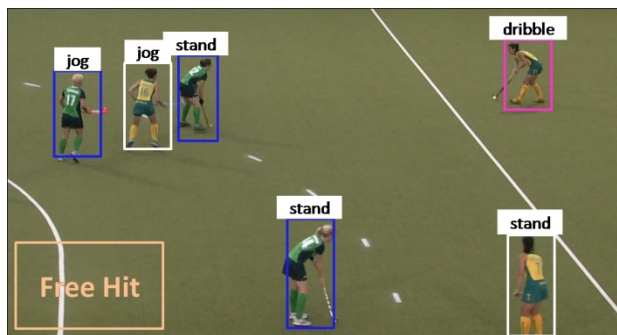
Introduction



Automatic Environmental Surveillance



Assisted Living



Sport Video Analysis



Human Computer Interaction

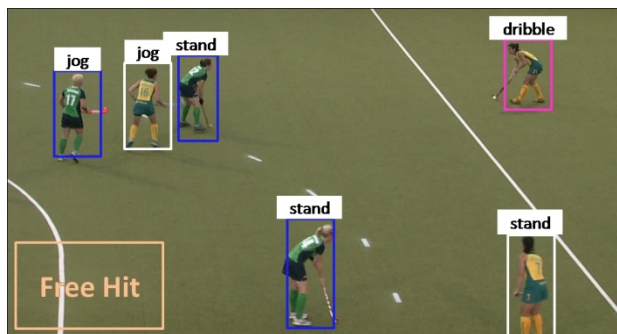
Introduction



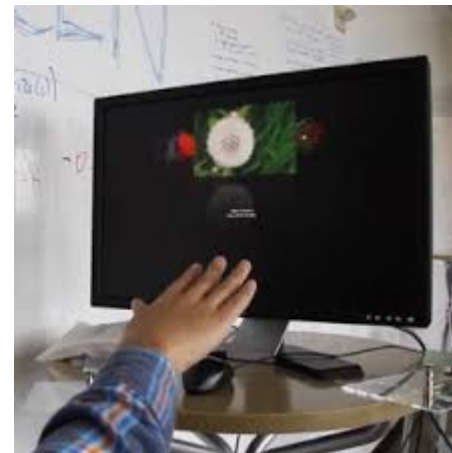
Automatic Environmental Surveillance



Assisted Living **Sensors ?**



Sport Video Analysis



Human Computer Interaction

Introduction



Wearable Sensors

- Extensive calibration
- Restricted natural movement



Vision Sensors

- Flexibility
- Markless
- Inexpensive
- Non-obtrusive

Introduction



Depth images

- Each pixel presents the distance between captured object and the camera.
- Motion ambiguities could be by passed.

Proposed Method

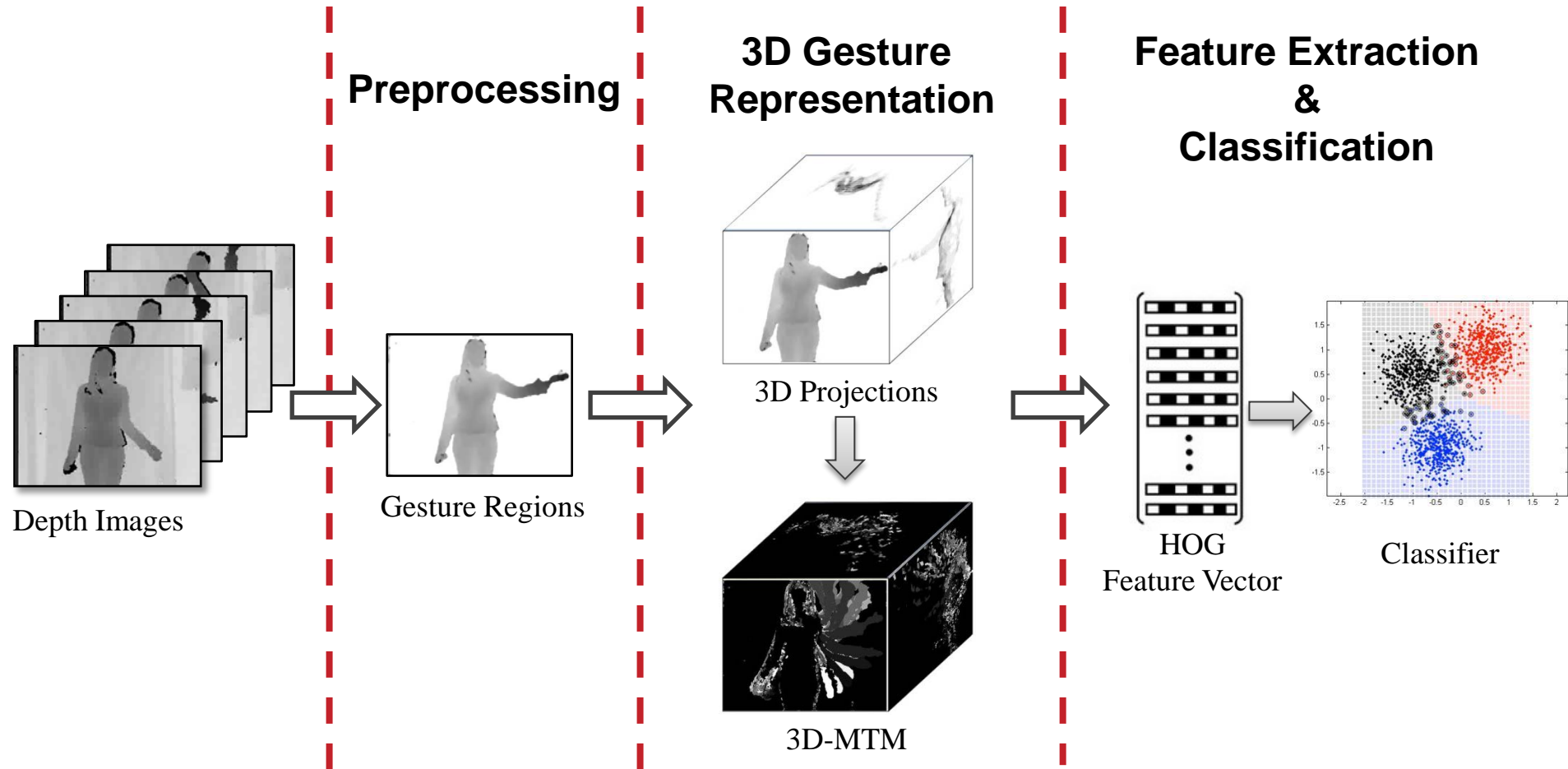
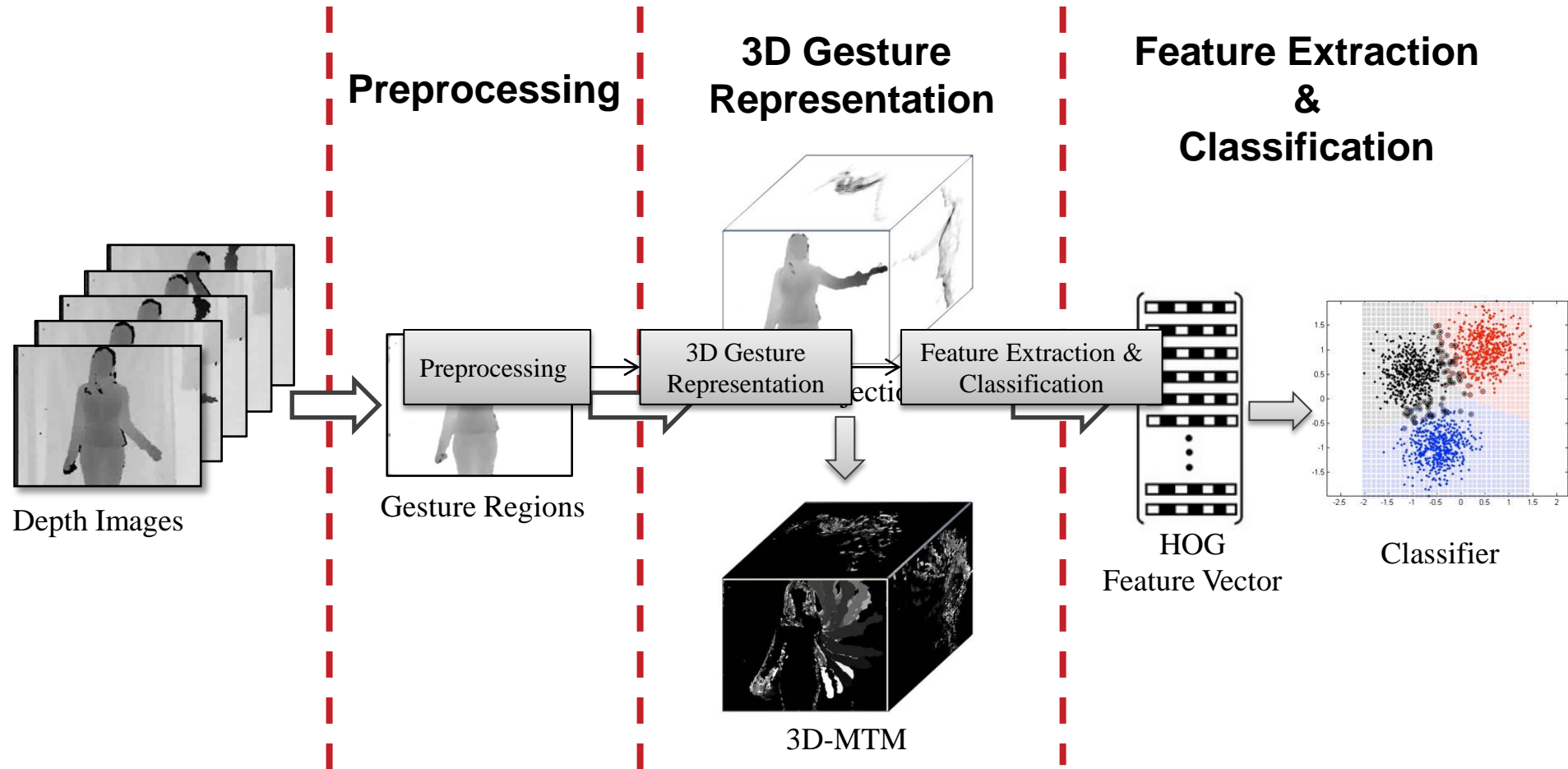
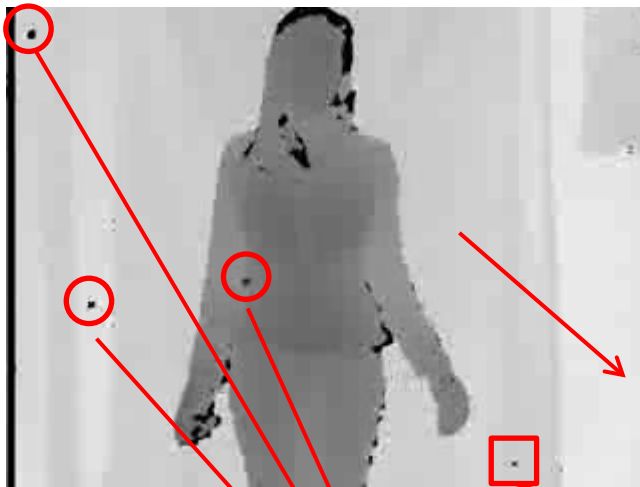


Fig. The general framework of the proposed method

Proposed Method

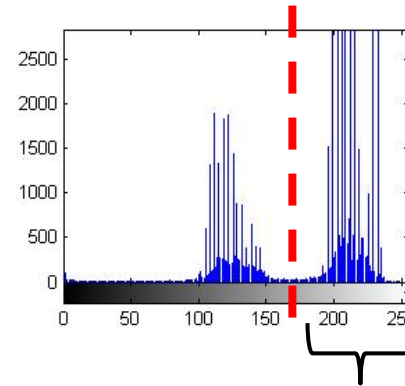


Proposed Method



background

noise



Background

- Otsu's method¹

101	69	0
56	255	87
123	96	157

- Median Filter

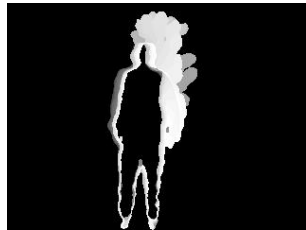
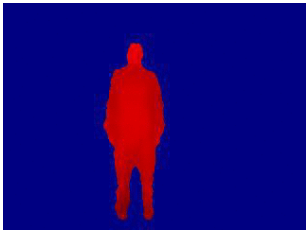
0	56	69	87	96	101	123	157	255
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1. Otsu, Nobuyuki. "A threshold selection method from gray-level histograms." 1975.

Proposed Method



- **Motion History Image (MHI)¹**



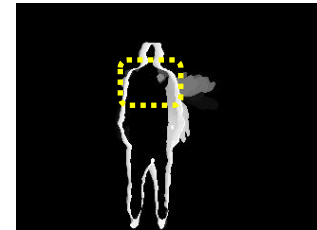
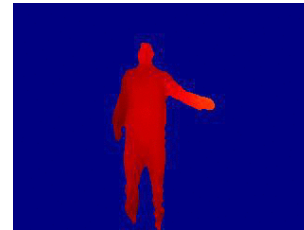
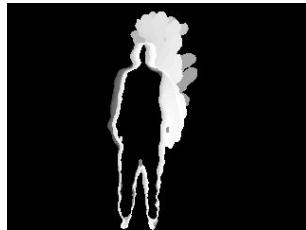
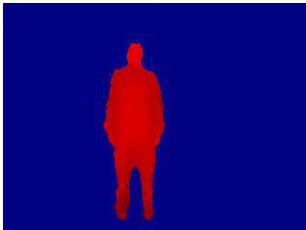
$$H(x, y, t; \tau) = \begin{cases} \tau & \text{if } \Psi(x, y, t) = 1, \\ \max(0, H(x, y, t-1; \tau) - \delta) & \text{otherwise.} \end{cases}$$

1. Bobick, Aaron F., and James W. Davis. "The recognition of human movement using temporal templates", 2001.

Proposed Method



- **Motion History Image (MHI)¹**



Limitations:

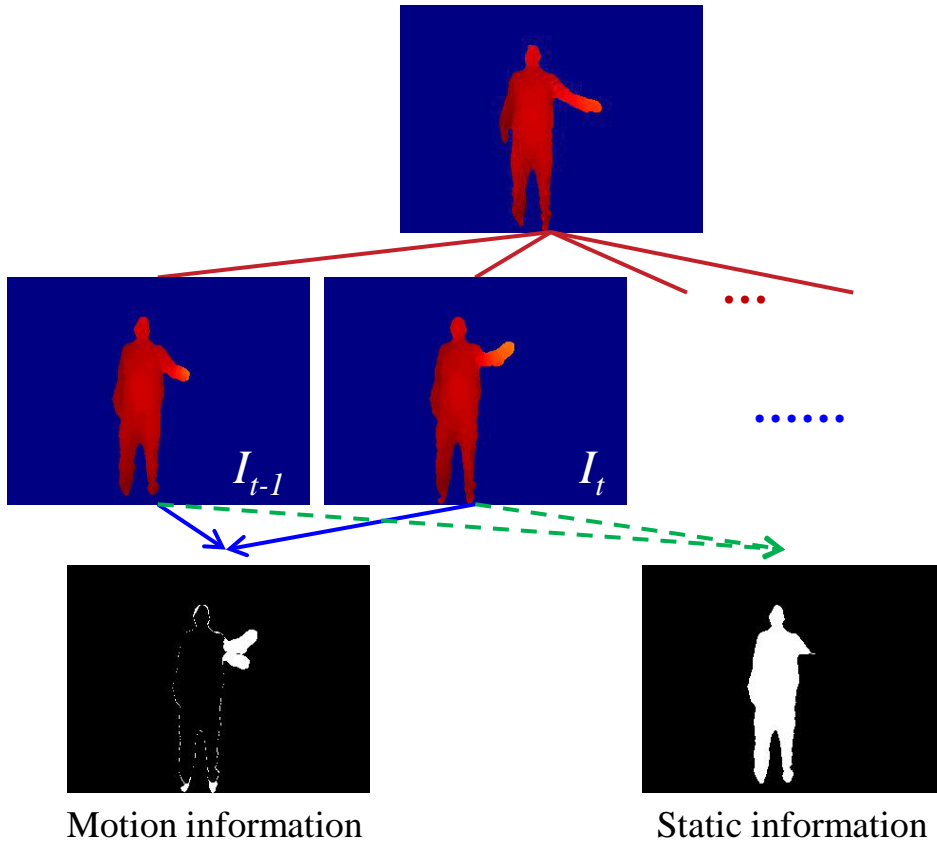
- fails to cover obstructed movements.
- information about static postures and repetitive movements is ignored.
- only encodes information along the xoy -plane

1. Bobick, Aaron F., and James W. Davis. "The recognition of human movement using temporal templates", 2001.

Proposed Method



• 2D Motion Trail Model (2D-MTM)



$$D_t = \begin{cases} I_1 & \text{if } t = 1 \\ |I_t - I_{t-1}| & \text{otherwise} \end{cases}$$

Motion update function:

$$\Psi_M(x, y, t) = \begin{cases} 1 & \text{if } D_t > \zeta_M, \\ 0 & \text{otherwise.} \end{cases}$$

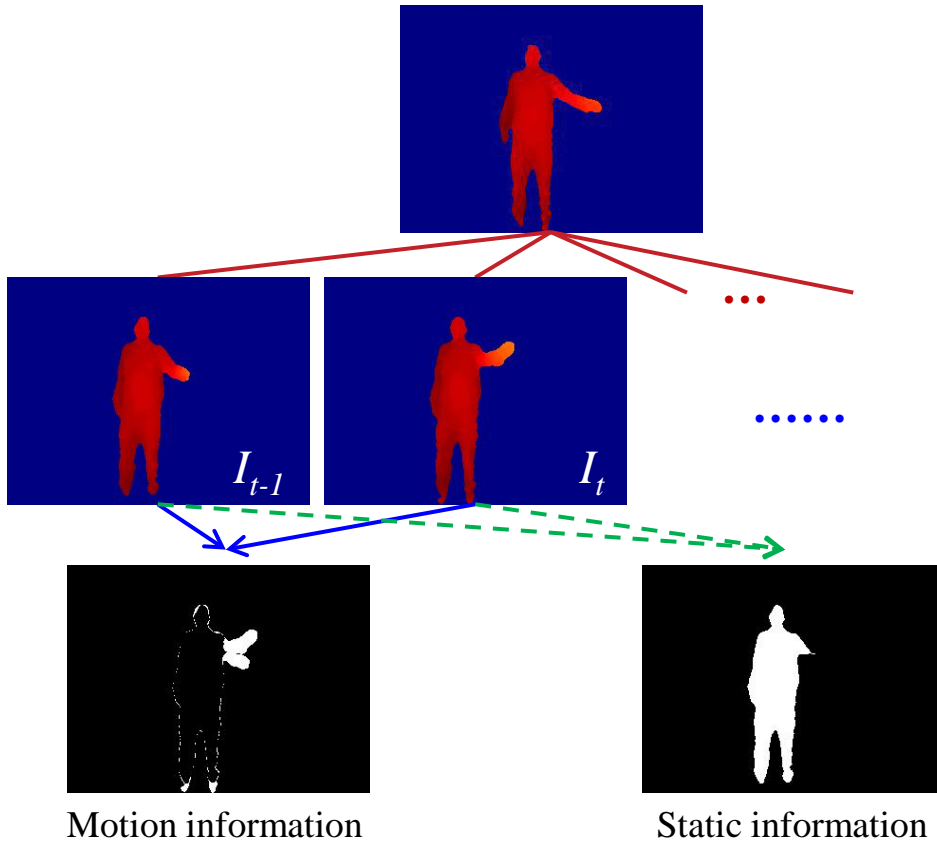
Static posture update function:

$$\Psi_S(x, y, t) = \begin{cases} 1 & \text{if } I_t - D_t > \zeta_S, \\ 0 & \text{otherwise.} \end{cases}$$

Proposed Method



• 2D Motion Trail Model (2D-MTM)



Depth motion history image (D-MHI):

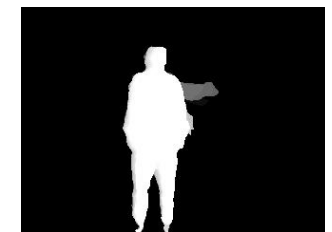
$$H_M(x, y, t) = \begin{cases} T & \text{if } \Psi_M(x, y, t) = 1 \\ H_M(x, y, t-1) - 1 & \text{otherwise} \end{cases}$$

Static posture history image (SHI):

$$H_S(x, y, t) = \begin{cases} T & \text{if } \Psi_S(x, y, t) = 1 \\ H_S(x, y, t-1) - 1 & \text{otherwise} \end{cases}$$



D-MHI

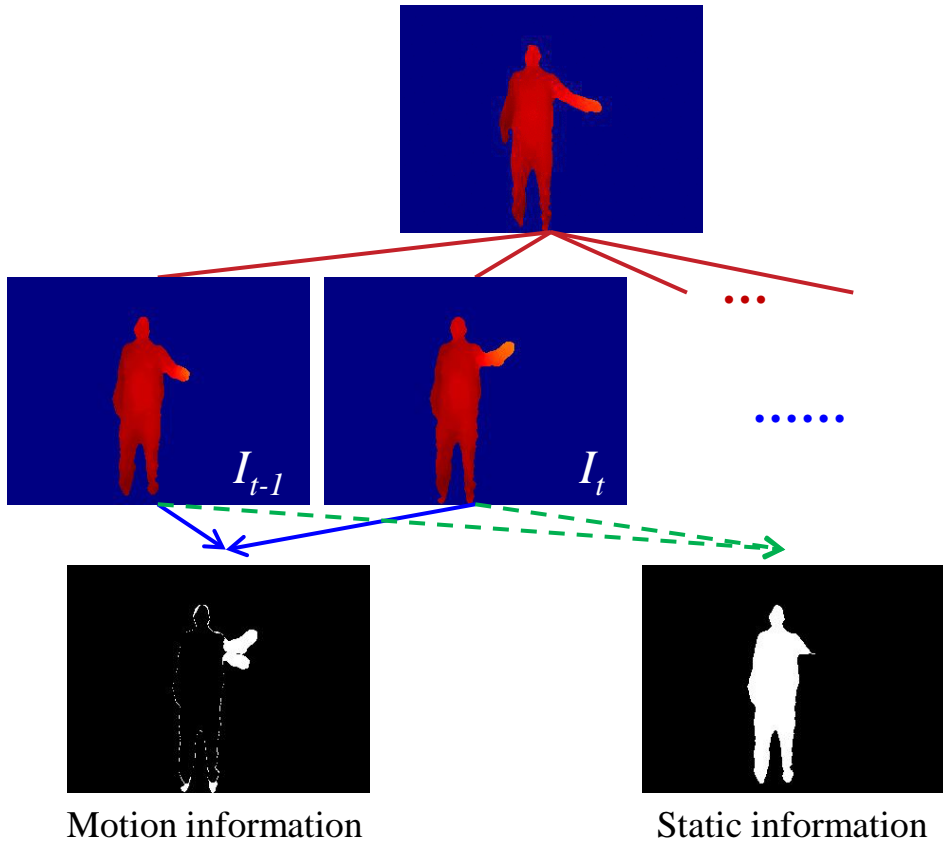


SHI

Proposed Method



• 2D Motion Trail Model (2D-MTM)



Average motion image (AMI):

$$A_M = \frac{1}{T} \sum_{t=1}^T \Psi_M(x, y, t)$$

Average static posture image (ASI):

$$A_S = \frac{1}{T} \sum_{t=1}^T \Psi_S(x, y, t)$$



AMI

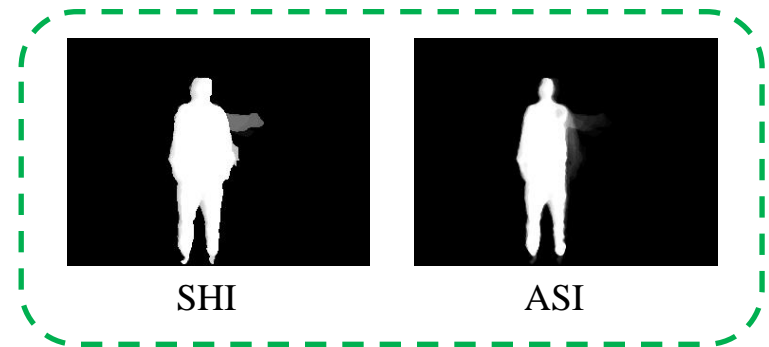
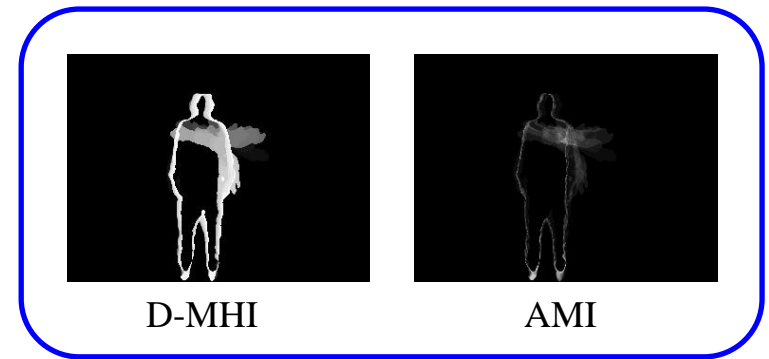
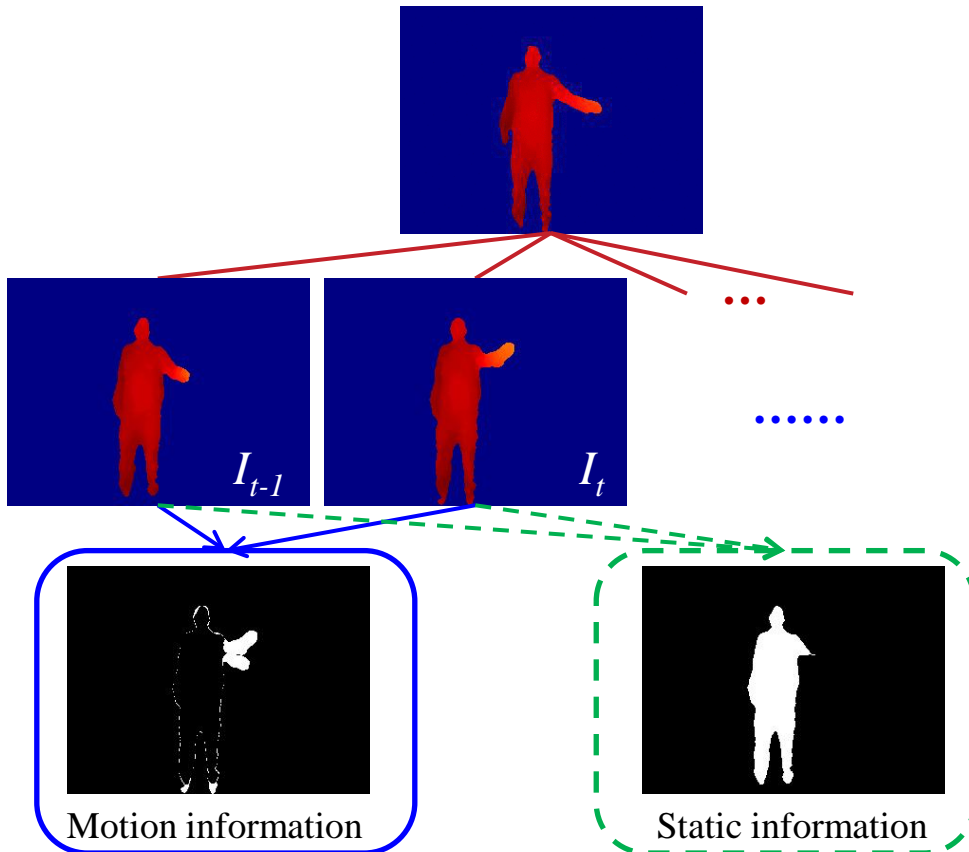


ASI

Proposed Method



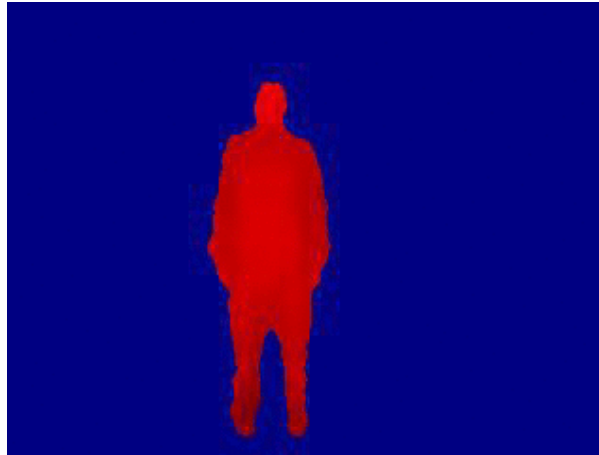
• 2D Motion Trail Model (2D-MTM)



Proposed Method



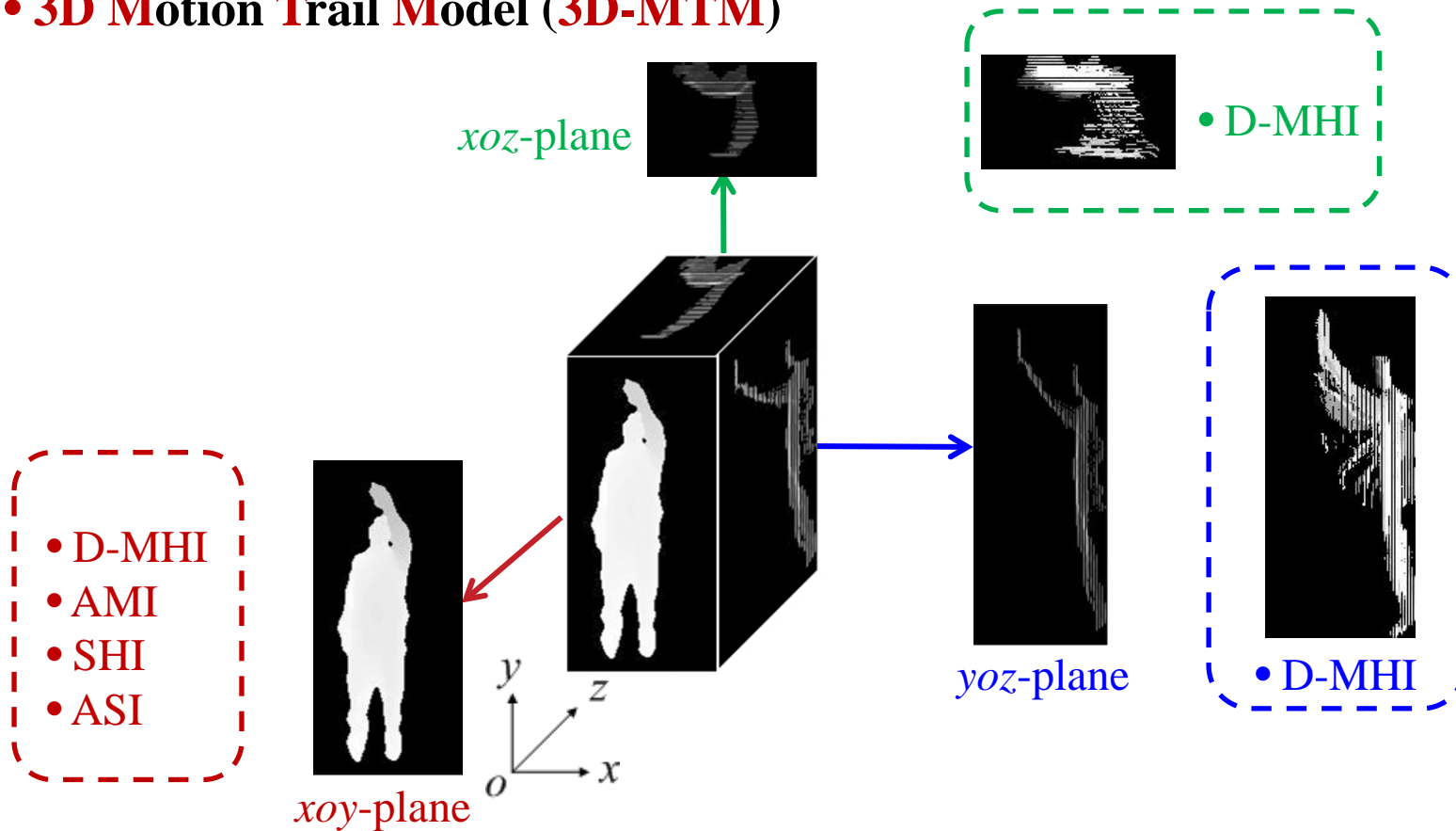
- **3D Motion Trail Model (3D-MTM)**



Proposed Method



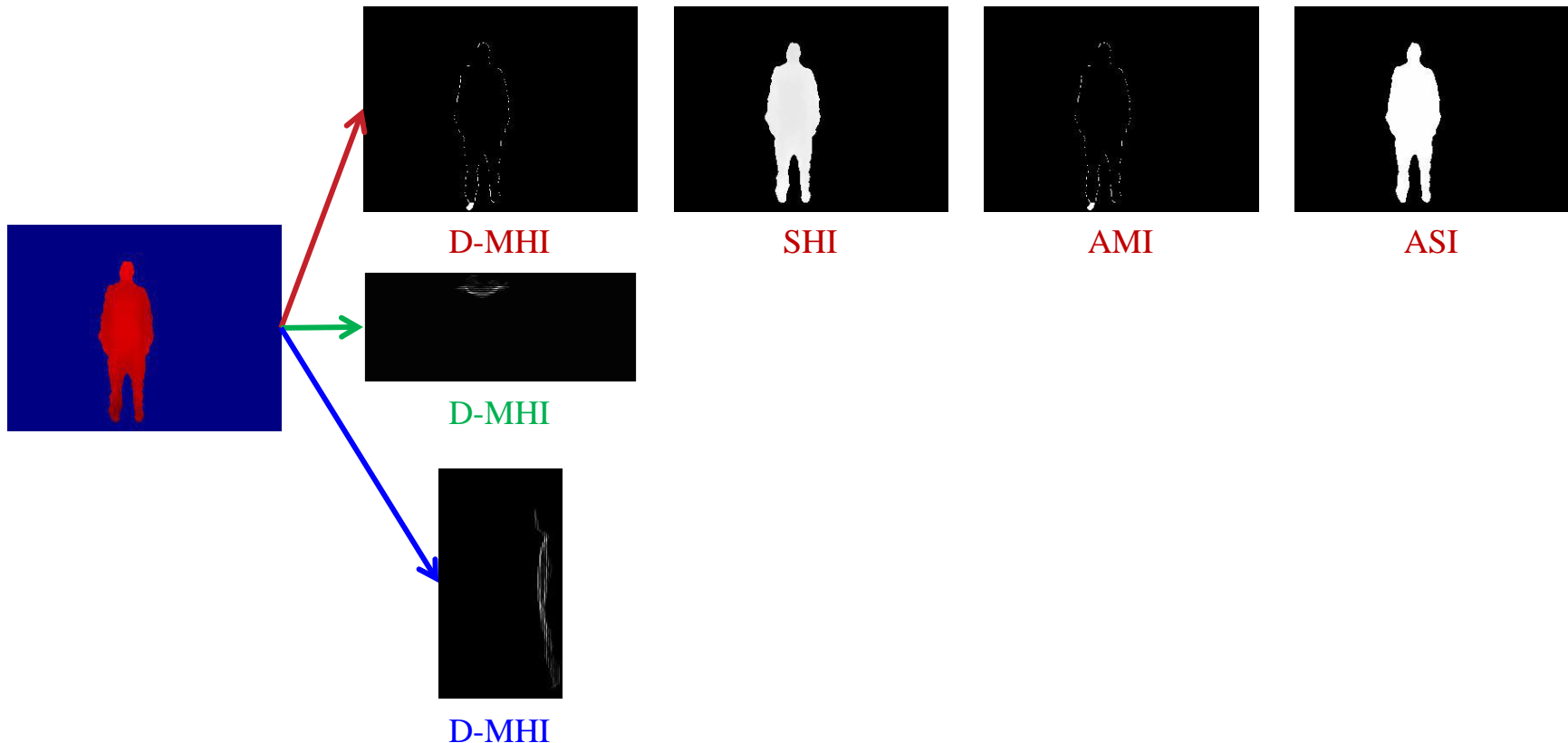
• 3D Motion Trail Model (3D-MTM)



Proposed Method



- **3D Motion Trail Model (3D-MTM)**



Proposed Method



- 3D-MTM

- is based on depth images
- contains the information of motion history, static posture history, average motion and average static posture
- represents movements from xoy -plane, xoz -plane and yoz -plane

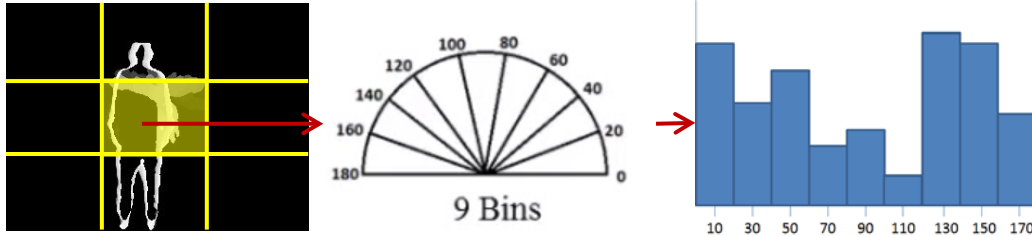
- MHI

- uses silhouette images
- only records the most recent movements
- only keeps motion information on a single plane

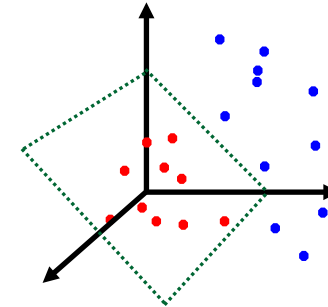
Proposed Method



- HOG



- Classification



Dimension of the feature vector:

$$N \times N \times B = 3 \times 3 \times 9$$

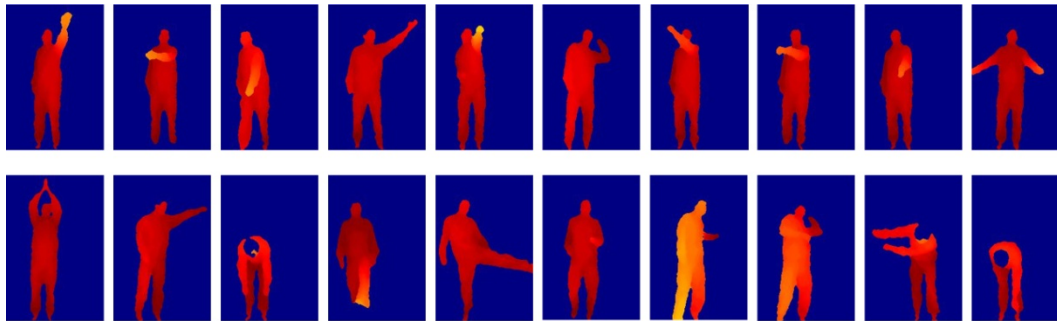
Dimension of 3D-MTM representation:

$$N \times N \times B \times 6 = 3 \times 3 \times 9 \times 6 = 486$$

- SVM
- Maximum Correlation Coefficient

Experimental Results

- **Datasets**



Sample frames from the MSR Action3D dataset



Sample frames from the ChaLearn gesture dataset

- **MSR Action dataset**
- 20 action types
- Each action is performed by 10 subjects for 2 or 3 times
- Resolution: 320×240

- **ChaLearn gesture dataset**
- Used for one-shot learning challenge
- Performed on the first 10 data batches
- Each test video contains 1 to 5 gestures

Experimental Results

MSR Action3D dataset

	Bag-of-3D-Points ¹	Proposed Method
T1-AS1	89.5%	96.0%
T1-AS2	89.0%	94.9%
T1-AS3	96.3%	97.3%
T2-AS1	93.4%	100.0%
T2-AS2	92.9%	97.5%
T2-AS3	96.3%	100.0%
CST-AS1	72.9%	73.7%
CST-AS2	71.9%	81.5%
CST-AS3	79.2%	81.6%

Tab. Recognition accuracy comparison of different subsets that are Test One (T1), Test Two (T2), and Cross Subject Test (CST)

1. Li, Wanqing, Zhengyou Zhang, and Zicheng Liu. "Action recognition based on a bag of 3d points". 2010

Experimental Results

One-shot learning ChaLearn gesture dataset

Method	Average error rate
Baseline	62.8%
Dynamic Time Warping	43.1%
Principle Motion	37.4%
MHI	37.6%
2D-MTM (ours)	24.4%
3D-MTM (ours)	21.7%

Tab. Performance comparison

Experimental Results

One-shot learning ChaLearn gesture dataset

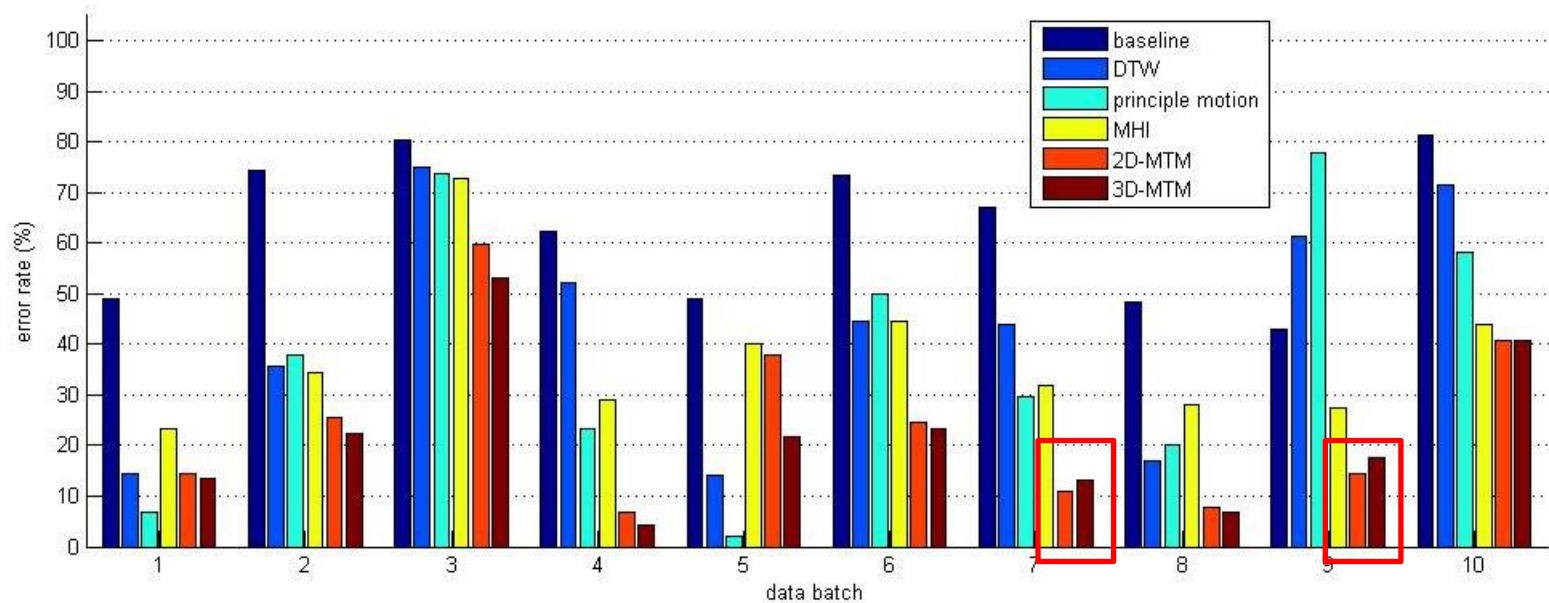
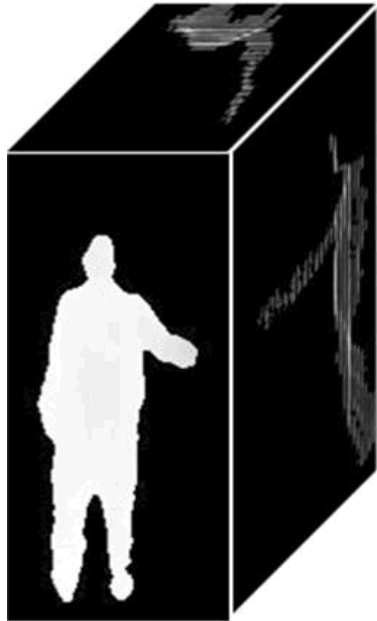


Fig. Results of the 10 data batches

Conclusions

- A 2D motion trail model (**2D-MTM**) is proposed to represent the motion information and static posture information of a gesture sequence.
- A novel 3D model (**3D-MTM**) is extensively proposed by projecting depth images onto other two planes, and it is shown to be robust to model gestures in 3D space.
- The proposed method based on 3D-MTM achieves competitive performance on MSR Action3D dataset and ChaLearn dataset..
- The future work will focus on gesture recognition on variant subjects to improve recognition performance in the Cross Subject Test.



Thank you